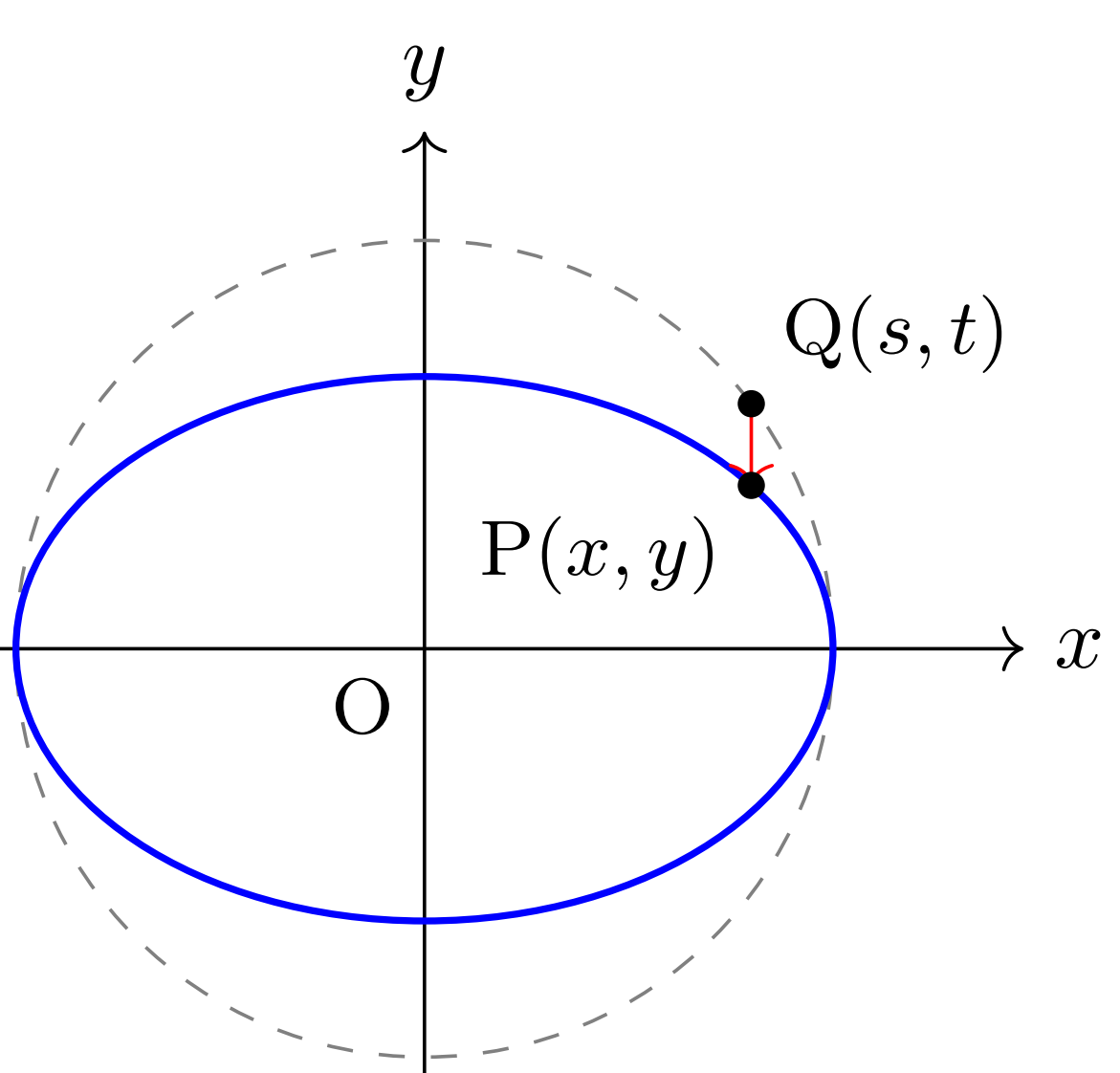

y
Q(s, t)
P(x, y)
x
O